

Warning: When working on your model.

Remove the propeller or unplug the motor or safe the propulsion system by some other means before performing Aura adjustments (including writing of settings), or other adjustments to your model.

Warning: Failsafe Function and Check

Perform a *failsafe check* before first flight and after making changes to your transmitter or the connection between your receiver and Aura.

- Safe your power system. Make sure Fuel powered engines are OFF. Remove the propeller from electric models.
- After checking control surface directions, turn your transmitter OFF. The blue Aura LED will come on indicating the Aura has detected a receiver failsafe condition. Confirm the controls react as follows:
 - If you are using a DSM2/DSMX Remote Receiver directly with the Aura, the Aura learns the failsafe values when you bind the Satellites to your Aura.
 - During a failsafe event, the Aura will set the throttle to the throttle value learned in the bind process.
 - If you completed the DSM2/DSMX transmitter action of the bind process with the bind plug in place, the remaining servo ports hold last position.
 - If you completed the DSM2/DSMX transmitter action of the bind process after removing the bind plug, the remaining servo ports go to learned failsafe positions.
 - If you use a receiver other than a DSM2/DSMX Remote Receiver, the Aura will use any failsafe values that you have setup between your transmitter and receiver (green Aura LED may also remain on).

Aura 8 Quick Start Guide Addendum

Warning: Use of 'Quick' Features

Before performing a *Quick Setup*, *Quick Trim*, or *Quick Check*, unplug all Servos, Turbine Controllers, etc. from ports configured to output throttle (typically S1). A conventionally programmed ESC/BEC is OK to leave connected to a throttle port (typically S1), but as always, remove the propeller or unplug the motor before performing these and other adjustments to your model.

With the default settings a servo that is connected to a throttle port will be driven to a full end point position during 'Quick Actions'. This may result in damage to the linkage or servo.